

CARDS FOR SCIENTISTS FROM THEIR NON-SCIENTIST RELATIONS



# Challenges associated with integration of machine vision algorithms into catch accounting programs

*an overview of the FMA EM Innovation project*

Pacific States Marine Fisheries  
Commission

NOAA

University of Washington  
Department of Electrical and Computer Engineering

Suzanne Romain [suzanne.romain@noaa.gov](mailto:suzanne.romain@noaa.gov)

Jennifer Ferdinand [jennifer.ferdinand@noaa.gov](mailto:jennifer.ferdinand@noaa.gov)

Jenq-Neng Hwang [hwang@uw.edu](mailto:hwang@uw.edu)

Craig Rose  
[craig.rose@noaa.gov](mailto:craig.rose@noaa.gov)

Paul Packer [paul.packer@noaa.gov](mailto:paul.packer@noaa.gov)

Jie Mei [jiemei@uw.edu](mailto:jiemei@uw.edu)

Graeme LeeSon [graeme.leeson@noaa.gov](mailto:graeme.leeson@noaa.gov)

Andy Kingman [andy.kingman@noaa.gov](mailto:andy.kingman@noaa.gov)

Aotian Zheng [aotianzheng@gmail.com](mailto:aotianzheng@gmail.com)

# Summary of EMI development and image types

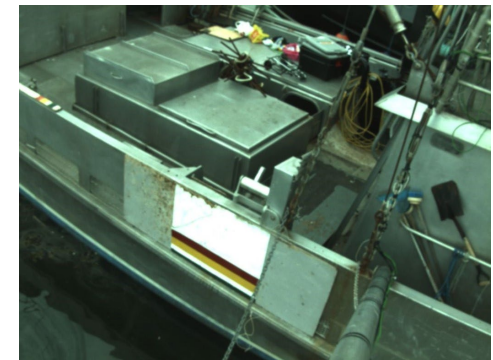
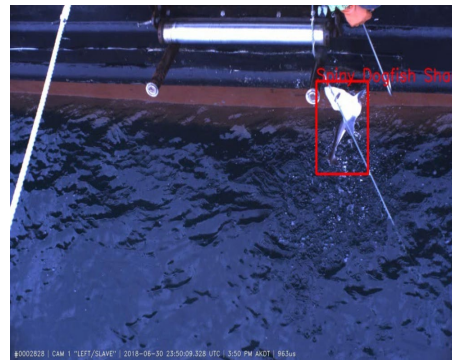
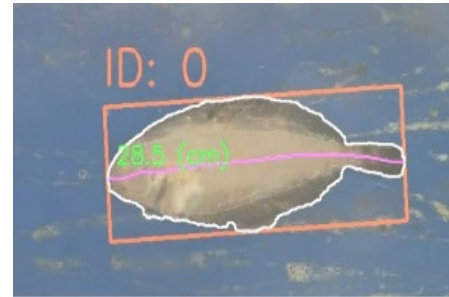
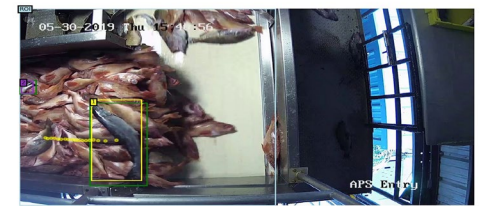
Rail, Camera Chute, Conveyor, Open Deck (Crew on Deck & Fish lengths on tables)

## Developed with

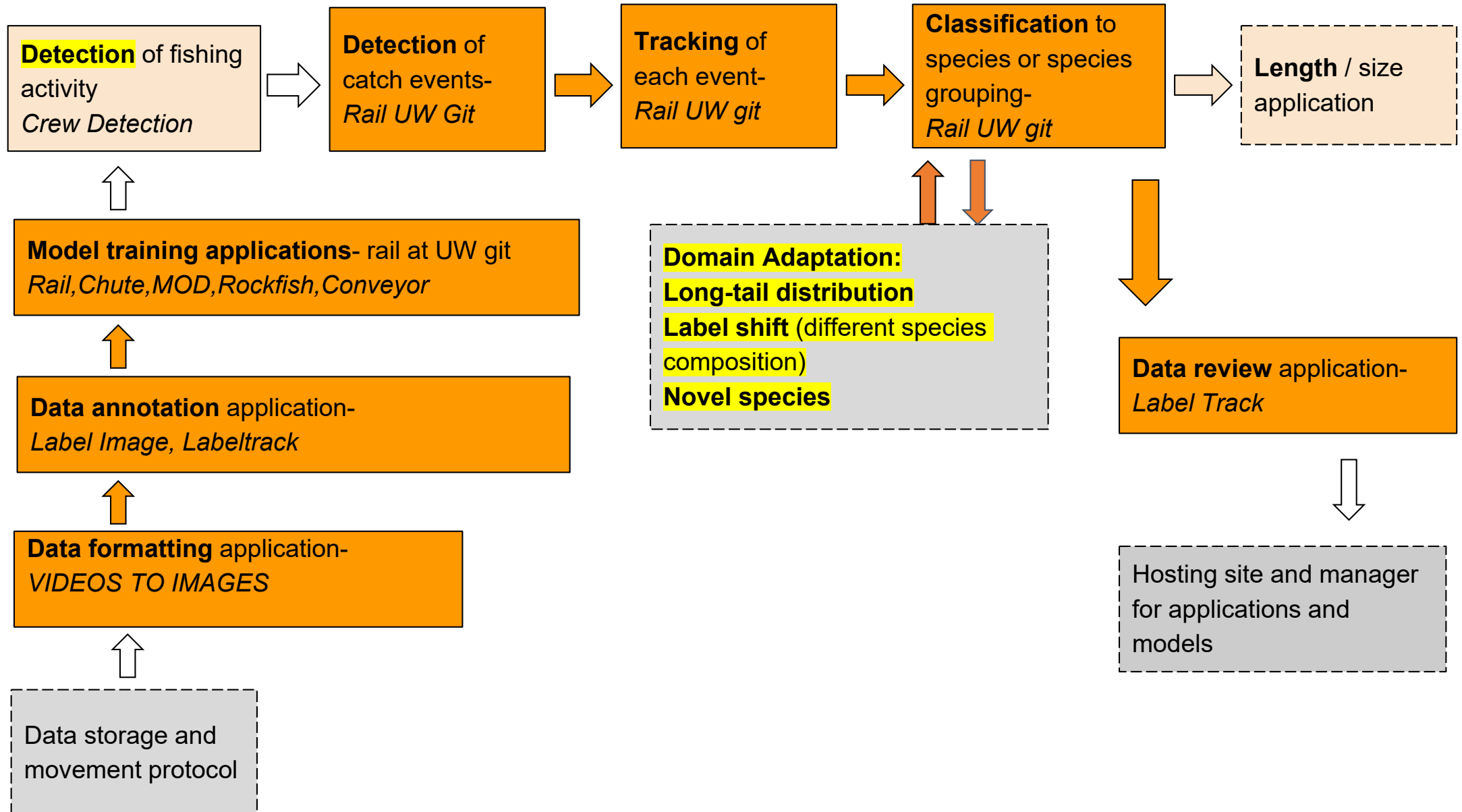
## Infer catch accounting information from images

- Controlled lighting/background images
- Outdoor captures of fishing
- Conveyor belts in plants

- Hauls
- Species Composition
- Census of species of interest
- Length



# Rail Catch Accounting Pipeline



# Machine Vision tool to select data of interest for review

## Human Presence Detector & Pose estimation in selected ROI

- 19,903 images from six camera angles were used
- Capable of detecting man on deck at a **98.87%** precision
- Refines identification of hauling periods
- Real-time processing was achievable
- Human pose estimation looks promising
- Requires thoughtful placement of region of interest to capture crew behaviour that can infer specific fishing activities

**Yolov3:** Redmon, Joseph, and Ali Farhadi. "Yolov3: An incremental improvement." arXiv preprint arXiv:1804.02767 (2018).

**OpenPose** [Cao, Z., Hidalgo, G., Simon, T., Wei, S.E. and Sheikh, Y., 2018. OpenPose: realtime multi-person 2D pose estimation using Part Affinity Fields. arXiv preprint arXiv:1812.08008.]



# Generalized Model...not so much

## Datasets

- 2015 chute data (8835 images with 27 classes)
- 2016 chute data (5032 images with 27 classes)
- Large (domain or label shift) difference between training and testing datasets
  - Slight species variations
  - Different camera color responses
  - Different distributions of species

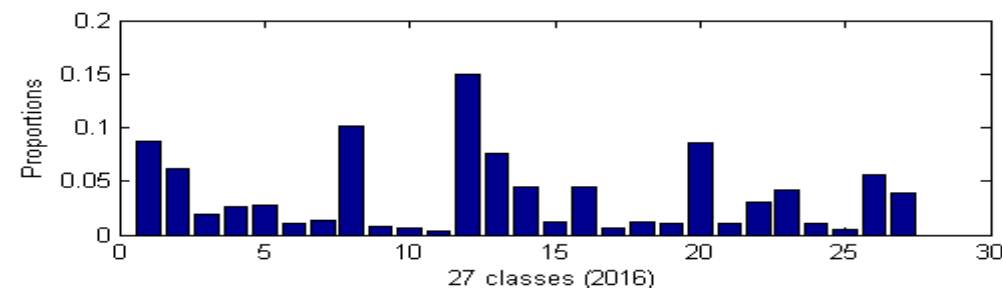
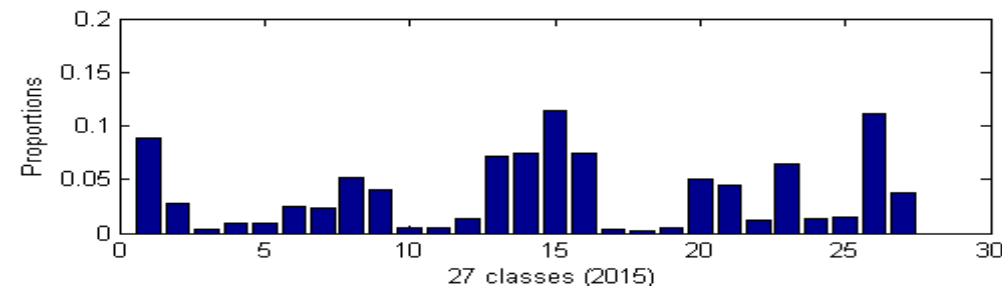
## Full Trainings

Training Data	Testing Data	Accuracy (%)
2015	2015	96.1
2016	2016	98.5
2015+2016	2015+2016	96.9

## Training with smaller percentages

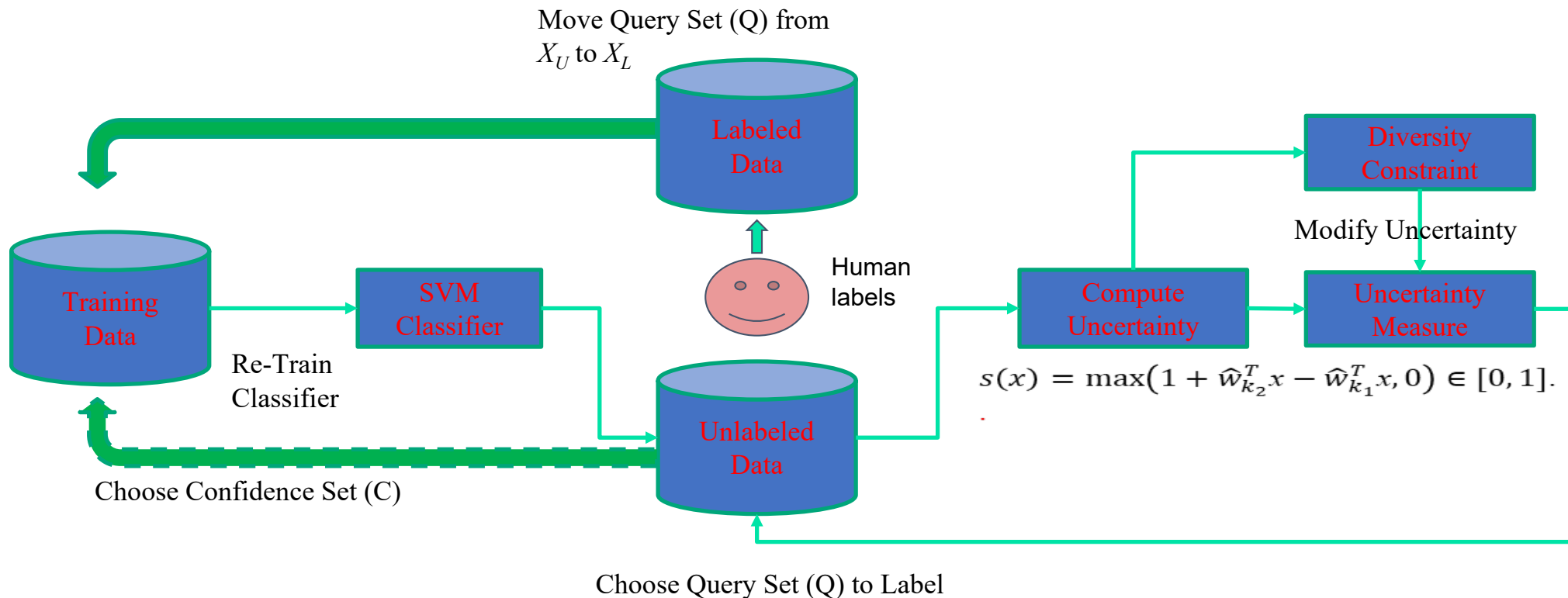
Training Data	Testing Data	Acc (%)
2015 dataset (5%)	2015 dataset (95%)	83.9
2016 dataset (5%)	2016 dataset (95%)	86.6
2015 dataset (100%)	2016 dataset (100%)	69.5
2015 dataset+2016 dataset (5%)	2016 dataset (95%)	88.1

## Changes Species Distributions (Label Shift)



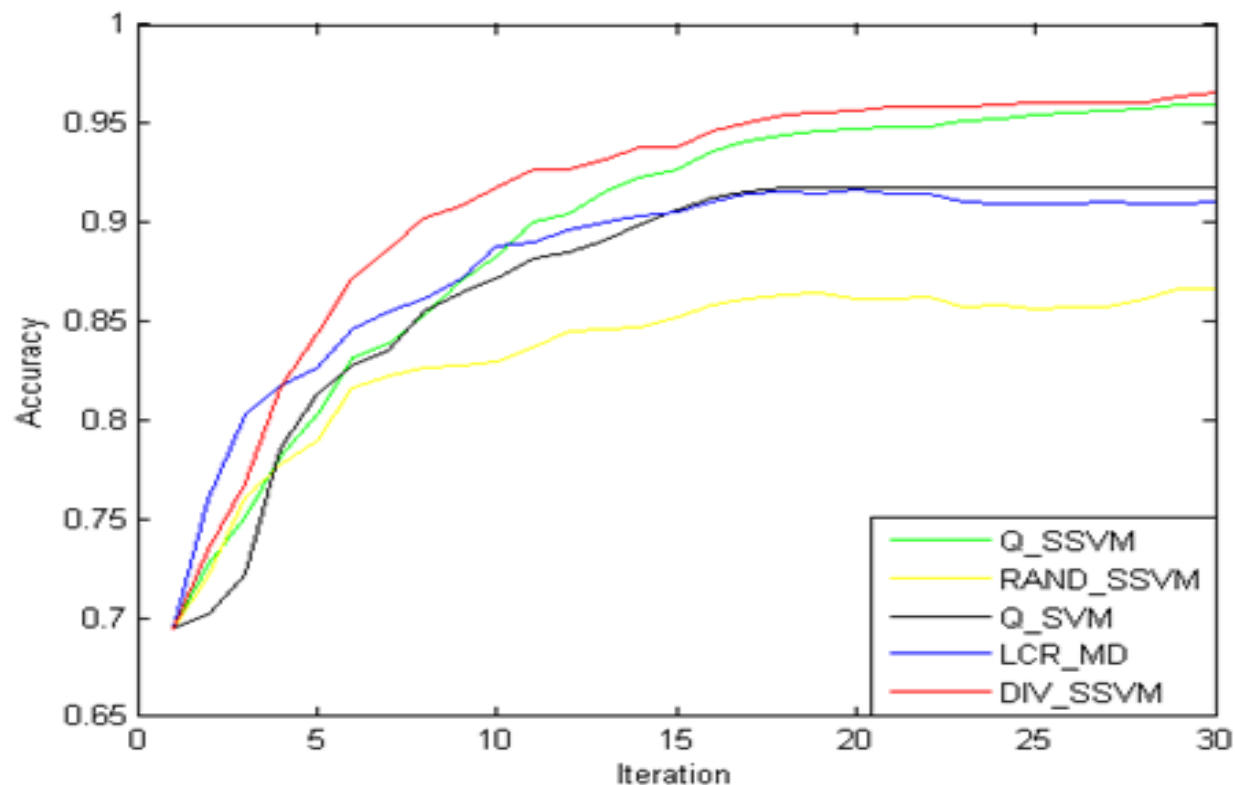
# Query Learning (Semi-Supervised Incremental Learning) to Solve both Domain and Label Shift

- Requires Human review resources
- Goal: **iteratively** select **informative** samples for human labeling to improve the performance of the classifier.



# Active Learning for Domain Adaptation

- Training set: 2015 dataset+2016 dataset (5%)
- Accuracy: 96.8% (**88.1% to 96.8%**)



- Q\_SSVM: Query learning with semi-supervised learning without diversity constraint.
- RAND\_SSVM: Query learning based on random sample selection.
- Q\_SVM: Query learning without semi-supervised learning.
- LCR\_MD: (Leng et al. 2013).
- **DIV\_SSVM**: Query learning with both semi-supervised learning and diversity constraint.

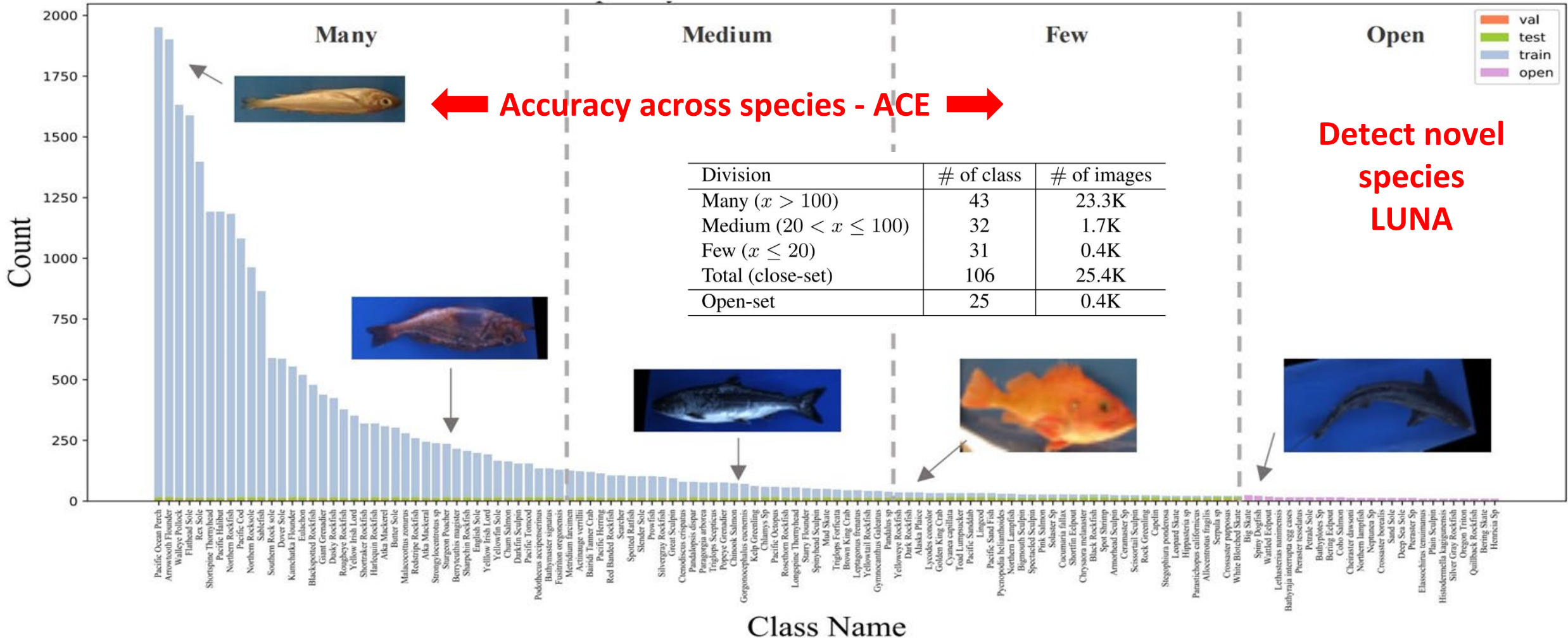


# EMI image collection: Long Tailed Distribution

Avoid Forgetting

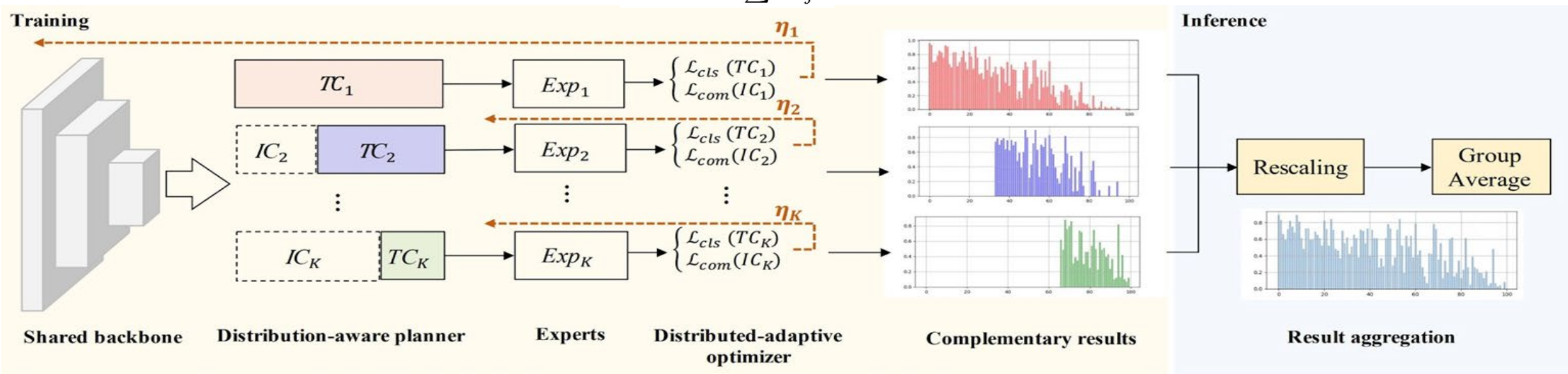
Transfer Knowledge

Sensitivity to Novelty



# Domain Adaptation for long tailed distributions across all classes in one shot: ACE: Ally Complementary Experts

$$\eta_i = \eta_0 \cdot \frac{\sum_{c \in \mathcal{C}_i} n_c}{\sum^{\mathcal{C}} n_j}$$



TC: Target categories ← - - - : Back-propagation

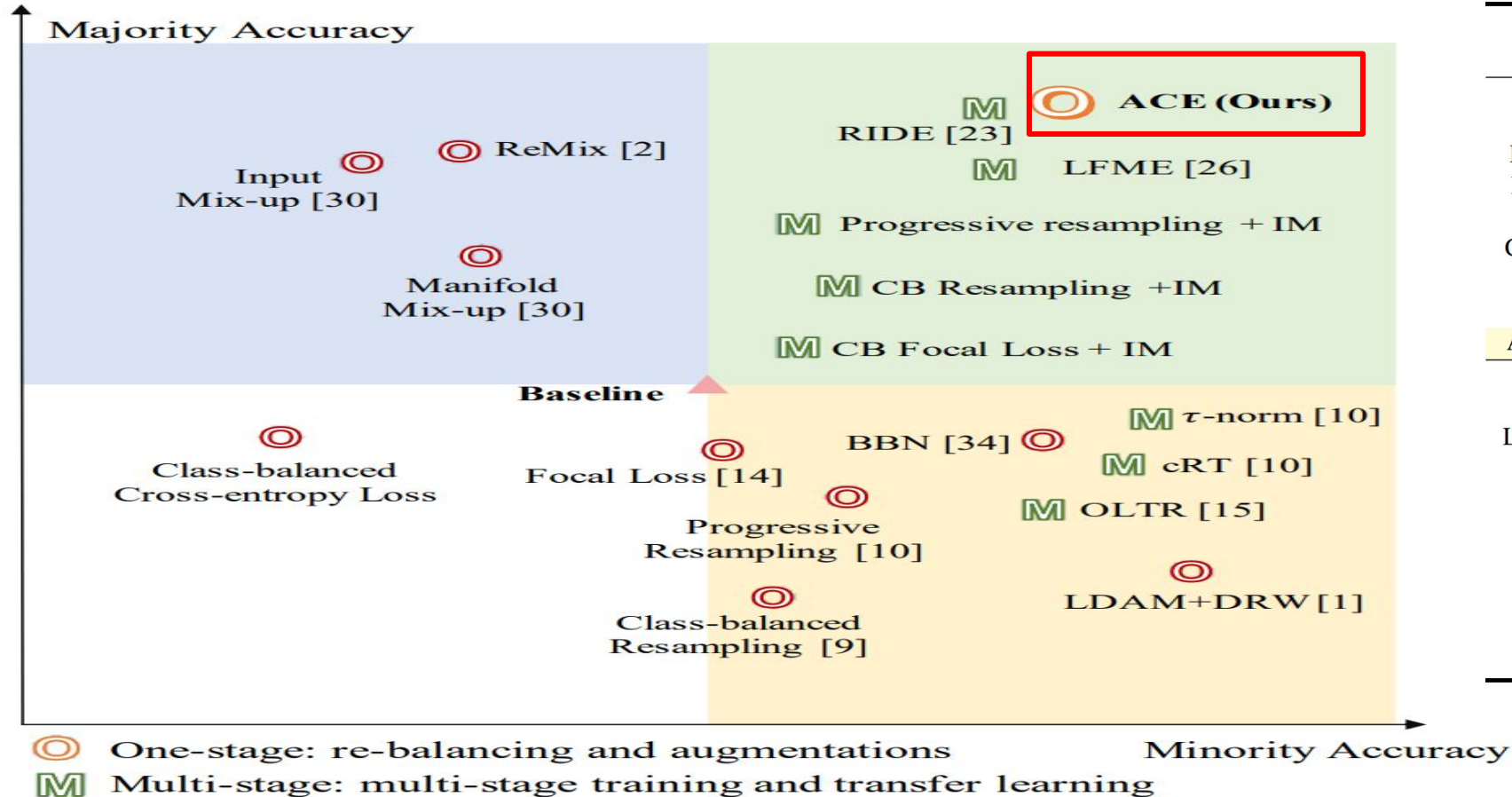
IC: Interfering categories

$$L^i = L_{cls}^i + L_{com}^i = - \sum_{\{TC_i\}} y \log(\sigma(z_i)) + \sum_{c_j} \|z_i^{c_j}\|^2$$

Cross-entropy loss ↓      Regularization ↓

# Domain Adaptation across all classes in one shot: ACE: Ally Complementary Experts

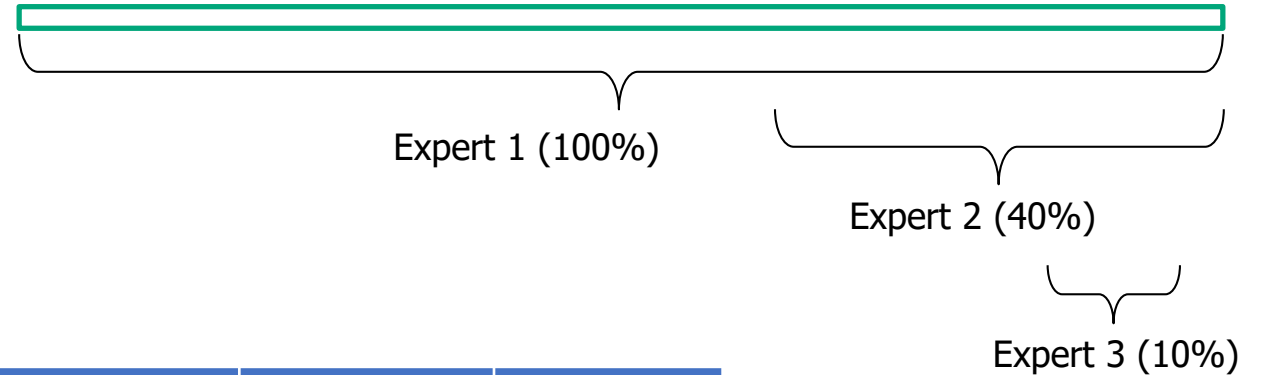
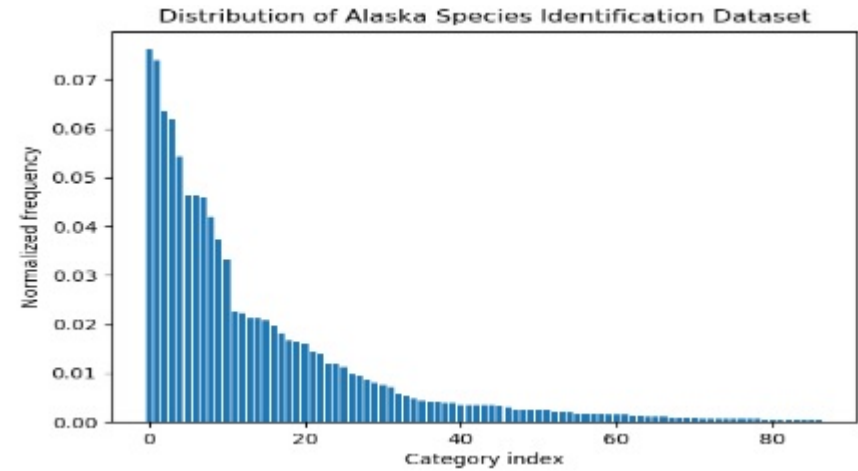
## Performance



Method	ImageNet-LT			iNaturalist
	Res10	Res50	ResX50	Res50
Baseline	20.9	41.6	44.4	66.1
FSLwF [5]	28.4	-	-	-
Range Loss [31]	30.7	-	-	-
Lifted Loss [18]	30.8	-	-	-
Focal loss [14]	30.5	-	-	60.3
CB Focal loss [3]	-	-	-	61.1
BBN [34]	-	48.3	49.3	68.0
Logit Adj.[16]	-	51.1	-	66.4
<b>ACE (3 experts)</b>	<b>44.0</b>	<b>54.7</b>	<b>56.6</b>	<b>72.9</b>
OLTR [15]	34.1	-	46.3	63.9
NCM [10]	35.5	44.3	47.3	-
LDAM+DRW [1]	36.0	-	-	68.0
cRT [10]	41.8	47.3	49.5	65.2
$\tau$ -norm [10]	40.6	46.7	49.4	65.6
LWS [10]	41.4	47.7	49.9	65.9
CAM [32]	43.1	-	-	70.9
LFME [26]	38.8	-	-	-
RIDE [23]†	-	54.4	55.9	71.4
RIDE [23]‡	-	54.9	56.4	72.2

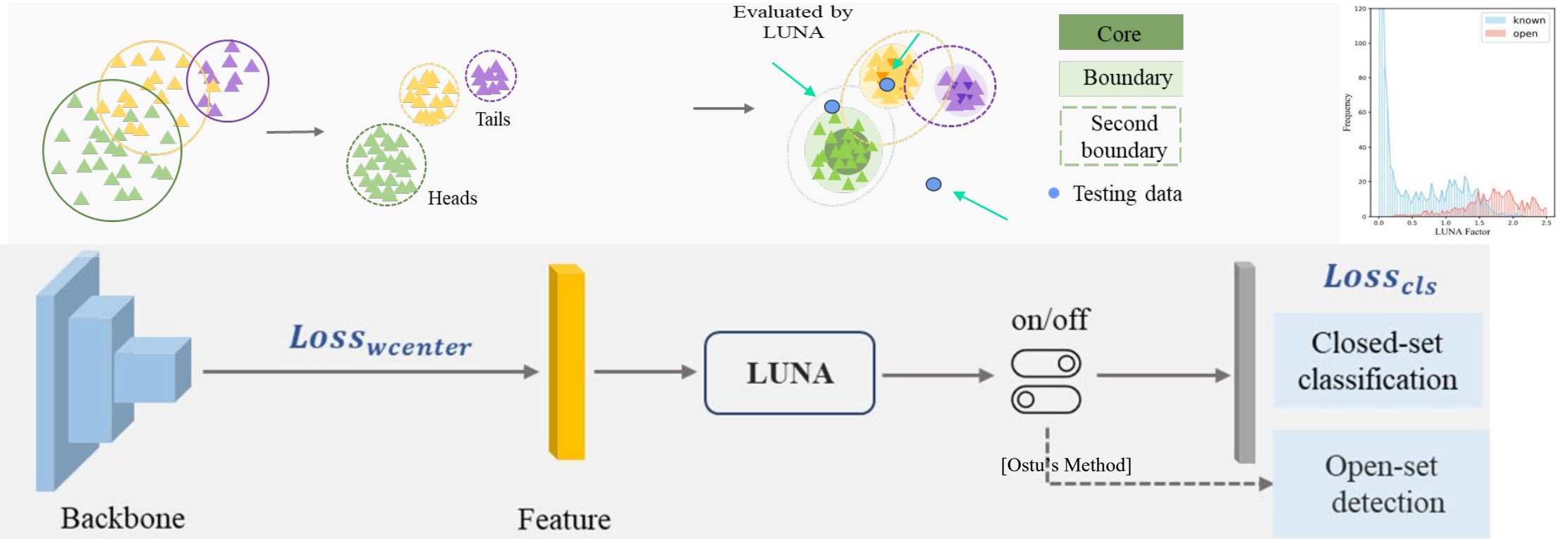
# Domain Adaptation across all classes in one shot: ACE: Ally Complementary Experts : Performance

- Alaska species ID dataset: 26.4k images for 87 classes
- Many-shot (>100 samples): 38 classes
- Medium-shot (>20 and <=100 samples): 33 classes
- Few-shot (<= 20 samples): 16 classes
- Imbalance factor =  $N_{max}/N_{min} = 193.5$
- Backbone: ResNet 50
- Number of experts: 3
- Experts 1, 2, 3 are trained with 100%, 40% and 10% of the dataset, respectively.



	<b>Overall Accuracy</b>	<b>Many</b>	<b>Medium</b>	<b>Few</b>
<b>ACE</b>	<b>95%</b>	<b>98%</b>	<b>97%</b>	<b>80%</b>

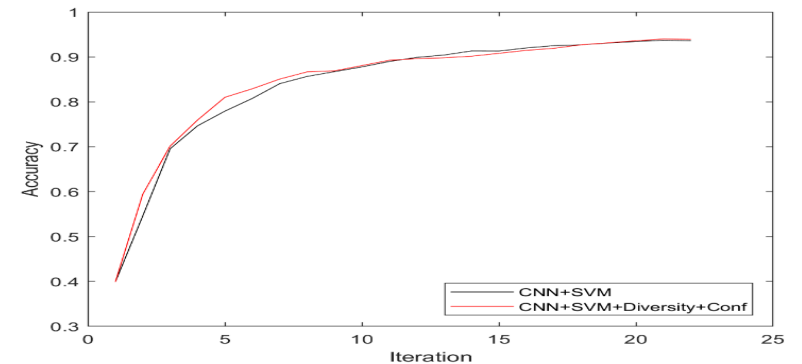
# Localizing Unfamiliarity Near Acquaintance (LUNA)



- **Non-Query Learning**
- 43-class (42+1 others)
  - Training, 6042 images
  - Testing, 698 images
  - **90%** samples used in the training.
  - Accuracy = **94.5%**.

- **New Class Discovery**
- From 27 to 42 classes
  - **5%** samples used in the training.
  - Accuracy = **93.9%**.

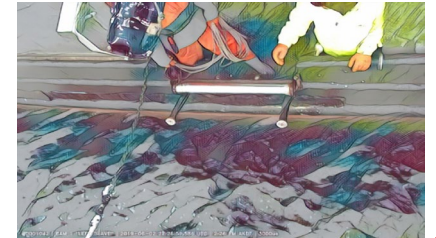
Jiarui Cai, et al., 2022



# Maintaining Classification Accuracy: Domain Adaptation

- Needed to address Changes to:
  - Camera angles
  - Background
  - Lighting conditions
  - Species composition

*Development image types*



*New data image types*

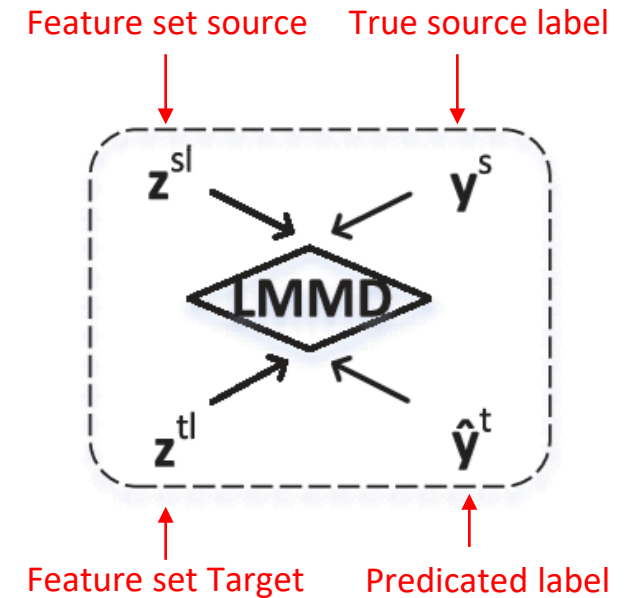
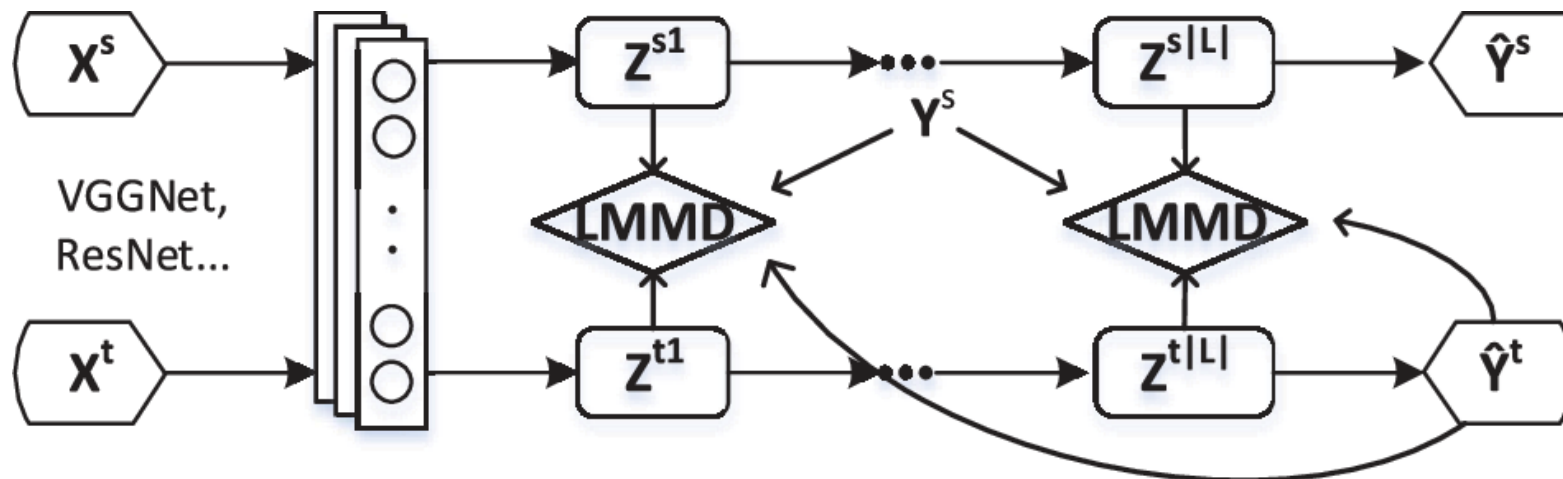
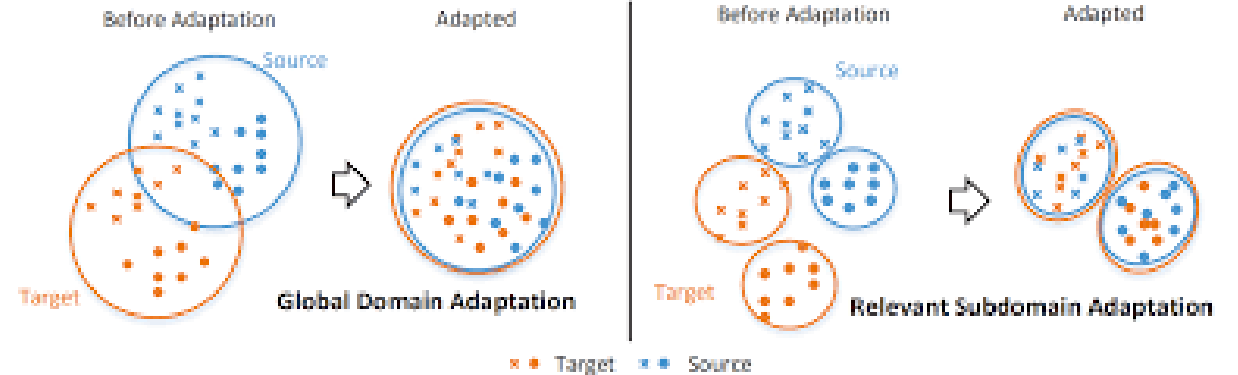


- Can be Unsupervised or Supervised, depending on human review resources
- Natural distribution of our image data challenges classification
- No “none of the above” option for machine vision classifiers, novel species need a specific strategy

# Deep Subdomain Adaptation Network for Image Classification

## Local Maximum Mean Discrepancy (LMMD)

- Uses labeled source data and unlabeled target data
- Extends the feature representation by aligning relative sub domains (IE; groups a halibut observation in source domain to another halibut observation in the target domain)



## Data Utilized

labeled image track data from base algorithm training

unlabeled image data from new vessels

## Training

Step-1: Pretrain Domain Adaptation universal (all views) and angle/vessel specific algorithms on labeled research ship data

Step-2: Fine tuning with LMMD on labeled research ship data and unlabeled target ship

A: Separately on different target ships

B: Jointly on combined target ships

## Evaluation

Using specific adapted models

Using one generic adapted model

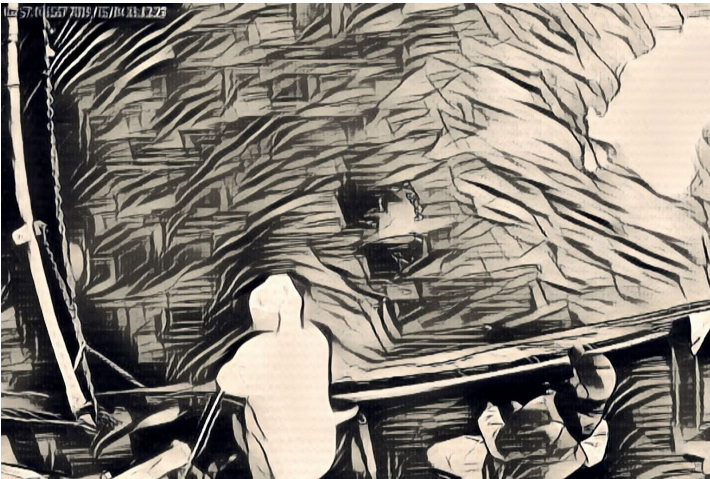
## Performance

Flat Classifier	# tracks	#frames	# species	No UDA	Generic UDA	Separate UDA
ForwardRollSV_2	87	7,136	10	24.14	57.47	<b>63.22</b>
ForwardRollSV_2	108		9	61.11	78.70	<b>83.33</b>
AftRollSV_1	90	6,205	7	26.67	95.56	<b>96.67</b>
AftRollSV_1	95		8	24.21	96.84	<b>97.89</b>
AftRollSV_2	13	3,926	4	23.08	<b>92.31</b>	84.62
AftRollSV_2	55		6	1.81	72.73	<b>85.45</b>
AftRollSV_2	22		4	31.82	86.36	<b>95.45</b>
ForwardRollSV_2	73	1,665	9	53.42	87.67	<b>90.41</b>
ForwardRollSV_1	40	1,148	5	32.50	<b>67.50</b>	65.00
Top Down_V1	72	2,115	6	6.94	45.83	<b>54.17</b>



# Implementation of Machine Vision Tools into a catch accounting program

While some applications can be generalized, data needs human configuration of regions of interest and vessel specific adaptations to extract useful information from the outputs



Multiple domain adaptation steps may be needed

Some image sets/types may not be viable with any domain adaptation strategy

Integrating machine vision tools will require

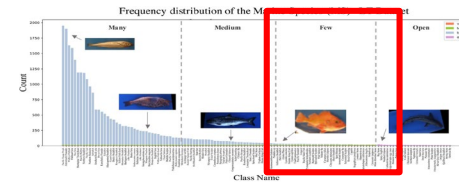
- Image type specific database and processing pipeline
- Configuration parameters for each vessel
- Domain adaptation strategy-could vary based on vessel or target species
- Review/ Audit protocols and staff
- Advance management of computing resources/balancing CPU GPU

## Top Down

Flat Classifier	# tracks	# species	No UDA	Generic UDA	Separate UDA	Gt tracks
Top Down_V1	72	6	6.94	45.83	<b>54.17</b>	yes

# Rail : Rare Species Data Mining Pipeline

Pacific Sleeper Shark



Data storage and movement protocol

- Vessel Configuration**
- Vessel Name
  - Trip Dates
  - FOV image
  - ROI Crew & Catch

**Hosting site manager for applications and models**

- Manage video and image input/output
- Model training set, Vessel configurations
- Optimize CPU/GPU performance (multithreading)
- User interface for database managers and auditors



GPS Hydraulic sensors



Human audit



Convert to jpgs

Fishing gear  
Bait  
Bird (on line or in air)  
Fish

Count of each individual catch

Group / Species  
Flatfish Roundfish  
Rockfish Shark  
Skate Invertebrate

Could be multiple applications

Select % for Data review

Detection of fishing activity  
*Crew Detection*

Detection of catch events

Tracking of catch event

Classification species/group

Domain Adaptation

Select % for refinement

Length / size application

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- Mei, J., J. Yu, J. Hwang, S. Romain, C. Rose, K. Magrane, G. LeeSon. 2022 [Unsupervised Severely Deformed Mesh Reconstruction \(DMR\) From A Single-View Image for Longline Fishing](#). Computer Science 2022 IEEE International Conference on Multimedia and Expo Workshops
- Mei, J. Jenq-Neng Hwang, S. Romain, C. Rose, B. Moore, and K. Magrane, 2021. “Absolute 3d pose estimation and length measurement of severely deformed fish from monocular videos in longline fishing,” Environmental Science ICASSP 2021 - 2021 IEEE International Conference on Acoustics, Speech and Signal Processing (ICASSP)
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- Wang, G., J. Hwang, C. Rose and F. Wallace. 2019. Uncertainty-based active learning via sparse modeling for image classification. *IEEE Transactions on Image Processing*, vol. 28, no. 1, pp. 316-329, Jan. 2019, doi: 10.1109/TIP.2018.2867913.
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